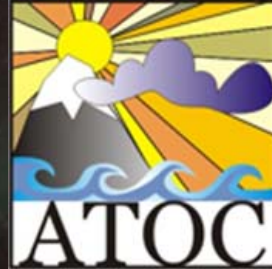


*Initial Results from the
Cloud,
Aerosol
Polarization
And
Backscatter
Lidar
at Summit, Greenland*



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Why did we put this lidar at Summit?



- Integrated **C**haracterization of **E**nergy, **C**louds, **A**tmospheric state, and **P**recipitation at **S**ummit (ICECAPS)
- Clouds affect the **M**ass and **E**nergy Budget of the Greenland Ice Sheet
- How do clouds impact the Greenland Ice Sheet?
 - Source: Precipitation => Mass Budget
 - Sink: Radiation => Energy Budget
- Significant sea level rise is predicted from a melting Greenland Ice Sheet



What are we observing? Cloud and precipitation phase

$$\delta = \frac{N_{\perp}}{N_{\parallel}}$$



Thanks to Ed Stockard for all the photos.

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How Do We Determine Orientation of Scatterers in CAPABL Polarization Measurements?



- CAPABL is polarization lidar described by the stokes vector lidar equation:

$$\vec{N} = \mathbf{OM}_{\text{RX}} \left[\left(G(R) \frac{A}{R^2} \Delta R \right) \mathbf{T}_{\text{atm}}(\vec{k}_s, R) \mathbf{F}(\vec{k}_i, \vec{k}_s, R) \mathbf{T}_{\text{atm}}(\vec{k}_i, R) \mathbf{M}_{\text{TX}} \vec{S}_{\text{TX}} + \vec{S}_B \right]$$

- When scatters may be assumed to be randomly oriented the depolarization ratio is derived as:

$$\delta = \frac{f_{11} - f_{22}}{f_{11} + f_{22}} = \frac{N_{\perp}}{N_{\parallel}} \quad \text{where } \mathbf{F}(\pi) = \begin{bmatrix} f_{11} & 0 & 0 & 0 \\ 0 & f_{22} & 0 & 0 \\ 0 & 0 & -f_{22} & 0 \\ 0 & 0 & 0 & f_{11} - 2f_{22} \end{bmatrix} \text{ is the randomly oriented backscatter matrix.}$$

- When scatters are not randomly oriented the depolarization ratio is derived as:

$$\delta = \frac{\mathcal{F}_{11} + \mathcal{F}_{33}}{\mathcal{F}_{11} - \mathcal{F}_{33}} = \frac{N_{\perp}}{N_{\parallel}} \quad \text{where } \mathbf{F}(\vec{k}_i, -\vec{k}_i) = \begin{bmatrix} \mathcal{F}_{11} & \mathcal{F}_{12} & 0 & 0 \\ \mathcal{F}_{12} & \mathcal{F}_{22} & 0 & 0 \\ 0 & 0 & \mathcal{F}_{33} & \mathcal{F}_{34} \\ 0 & 0 & -\mathcal{F}_{34} & \mathcal{F}_{44} \end{bmatrix} \text{ is the oriented backscatter matrix.}$$

We measure 3 planes of polarization to improve cloud property retrievals.



- By measuring N_{45} , we qualitatively determine if the scatters exhibit orientation through a quantity known as **diattenuation**:

$$\vec{N} = \begin{bmatrix} N_{||} \\ N_{45} \\ N_{\perp} \end{bmatrix}$$

$$\mathbf{F}(\vec{k}_i, -\vec{k}_i) = \begin{bmatrix} \mathcal{F}_{11} & \mathcal{F}_{12} & 0 & 0 \\ \mathcal{F}_{12} & \mathcal{F}_{22} & 0 & 0 \\ 0 & 0 & \mathcal{F}_{33} & \mathcal{F}_{34} \\ 0 & 0 & -\mathcal{F}_{34} & \mathcal{F}_{44} \end{bmatrix}$$

- Diattenuation allows us to unambiguously infer the form of the scattering matrix.

$$D_q = \frac{\mathcal{F}_{12}}{\mathcal{F}_{11}} = \frac{2N_{45}}{N_{||} + N_{\perp}} - 1 \quad \left\{ \begin{array}{l} = 0; \quad \delta = \frac{f_{11} - f_{22}}{f_{11} + f_{22}} \\ \neq 0; \quad \delta = \frac{\mathcal{F}_{11} + \mathcal{F}_{33}}{\mathcal{F}_{11} - \mathcal{F}_{33}} \end{array} \right.$$

L

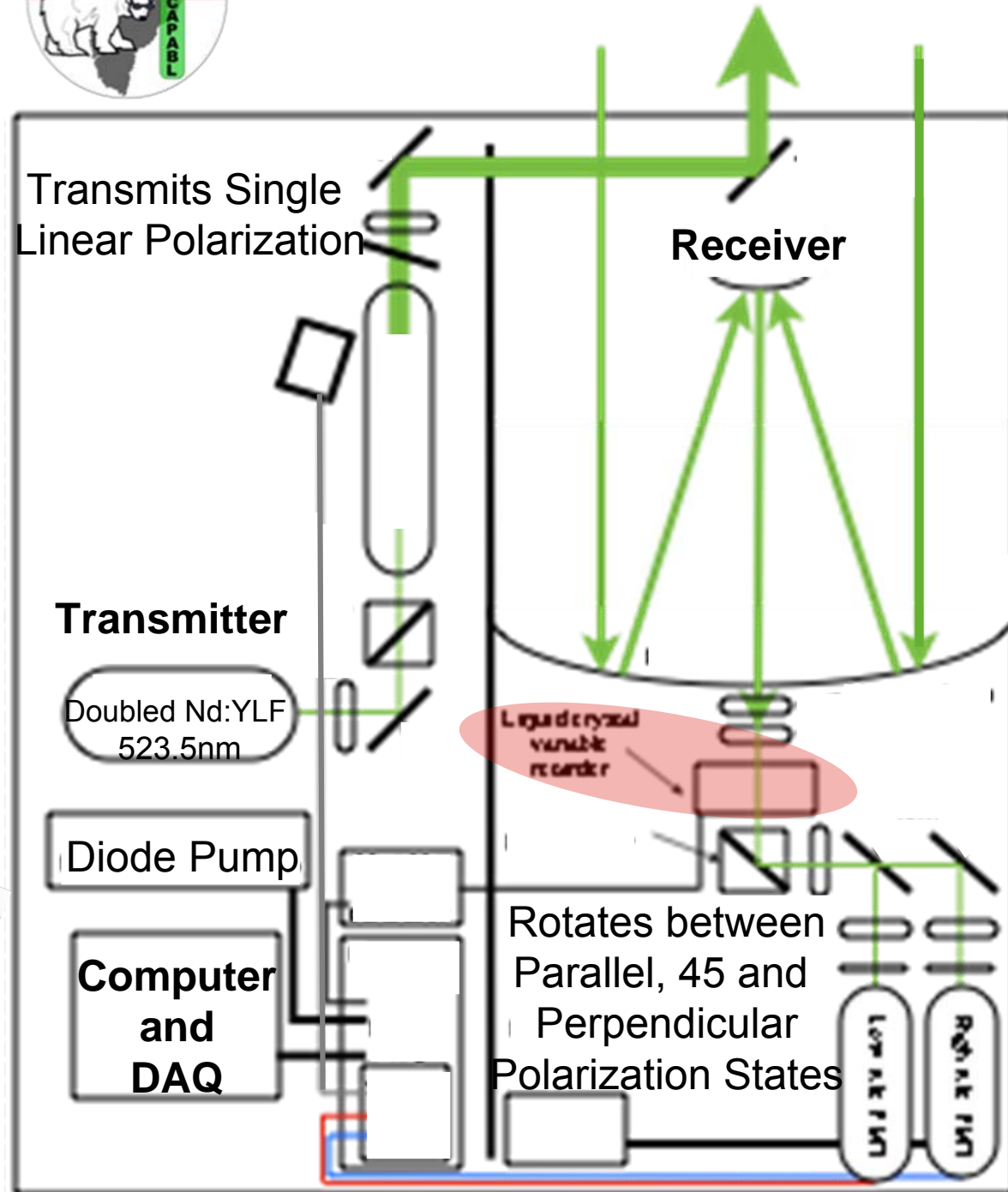
- **Triple linear polarization** measurement
- **30m** spatial and **5s** temporal resolution
- **24/7** automated operation with remote access.



L



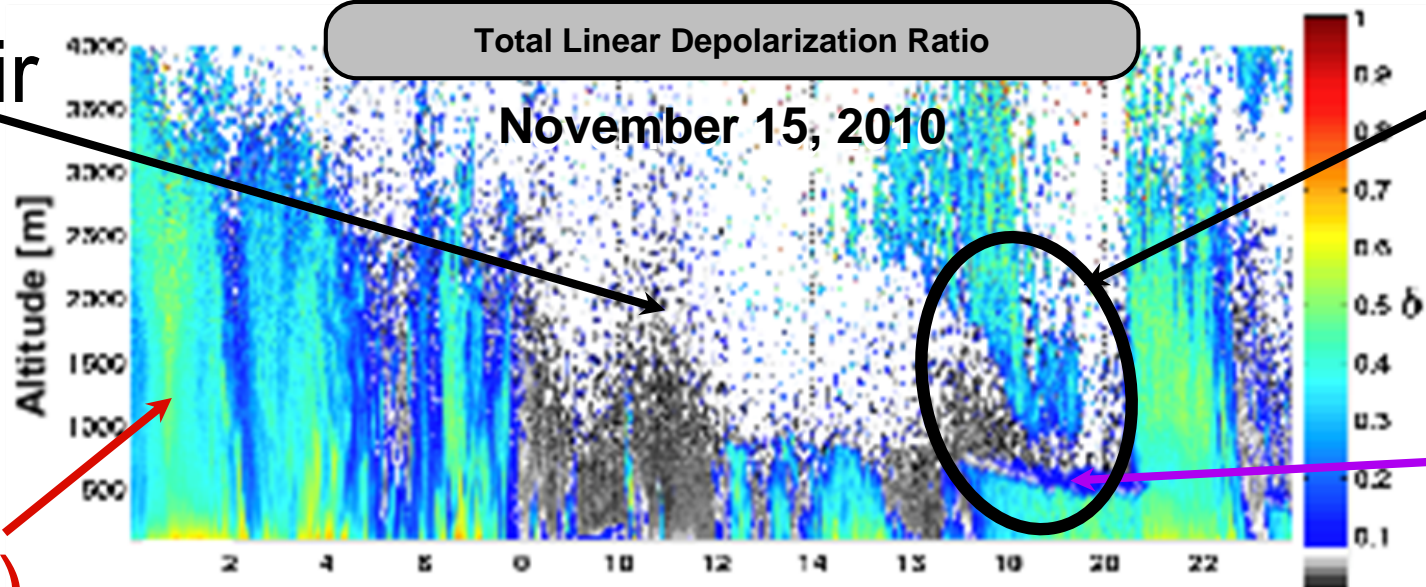
- **Triple linear polarization** measurement
- **30m** spatial and **5s** temporal resolution
- **24/7** automated operation with remote access.



Example Observation



Clear Air



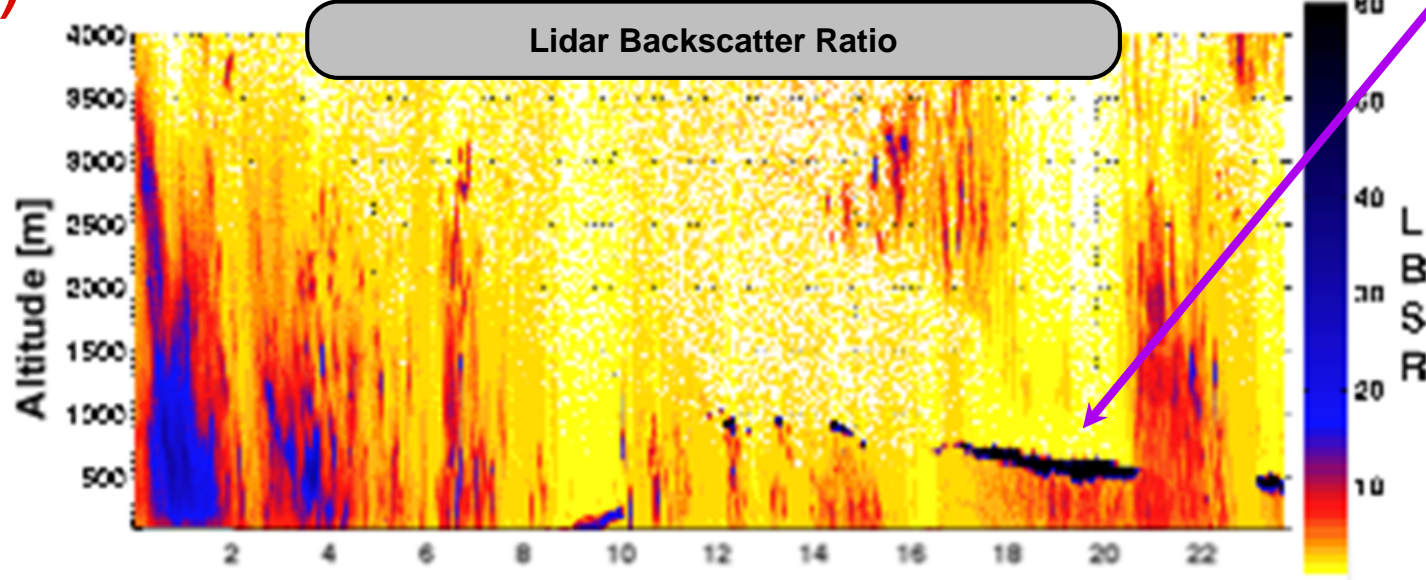
Total Linear Depolarization Ratio

November 15, 2010

Seeder-Feeder Cloud

Ice (High δ)

Liquid Layer (Near Zero δ and High LBSR)



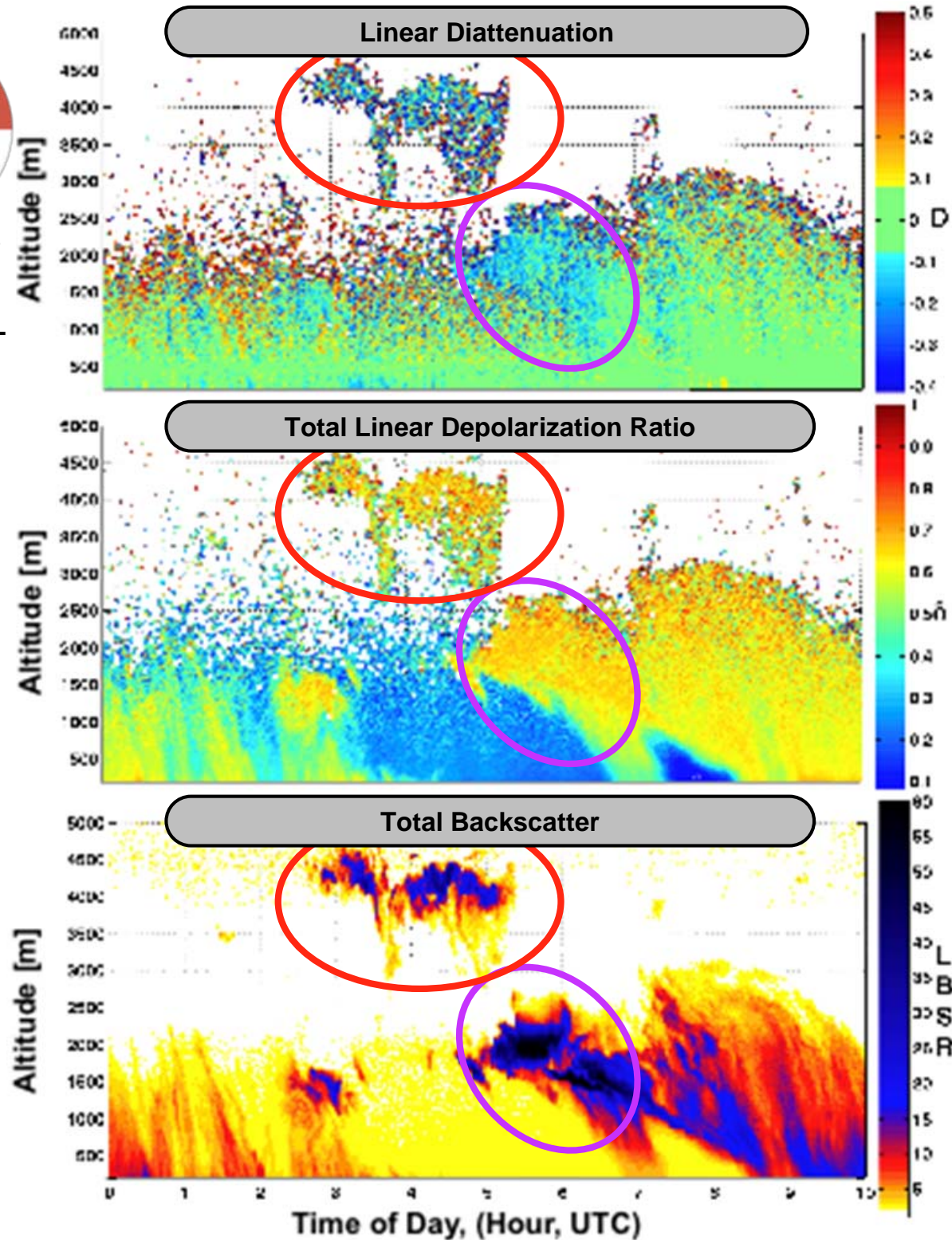
Lidar Backscatter Ratio

Time of Day, (Hour, UTC)

Observation of Diattenuation

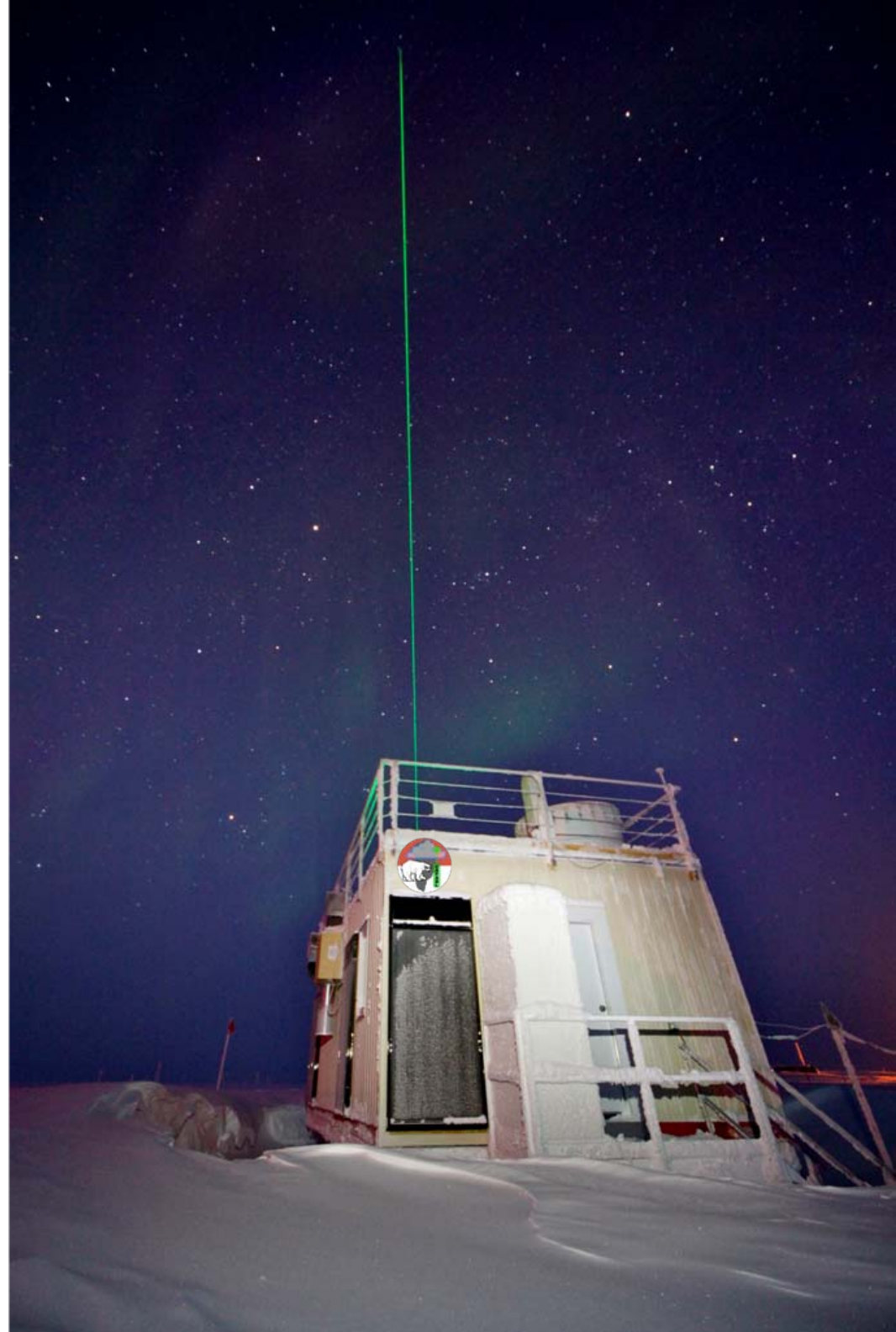


- On 18 February 2012, CAPABL observed two diattenuation signatures (Light blue in top panel).
- Cirrus cloud
 - Expected regime for oriented crystals as shown by observations from CALIPSO
- Cumulus
 - Unexpected particle orientation due to turbulence from strong precipitation
 - Enhancement of linear depolarization in area of strong diattenuation



Conclusions

- CAPABL can simultaneously determine:
 - Cloud phase (linear depolarization ratio) of randomly oriented scatterers
 - Variations in the diattenuation of the scatterers, which may be used to interpret the presence of HOIC.
- Diattenuation measurements improve the overall quality of cloud phase measurements (less than 2% error in linear depolarization ratios) by reducing uncertainty about the orientation of scatterers.
- Current observation provides a first demonstration of operationally detecting HOIC by direct polarization determination.



Thank You



Where did we put it?



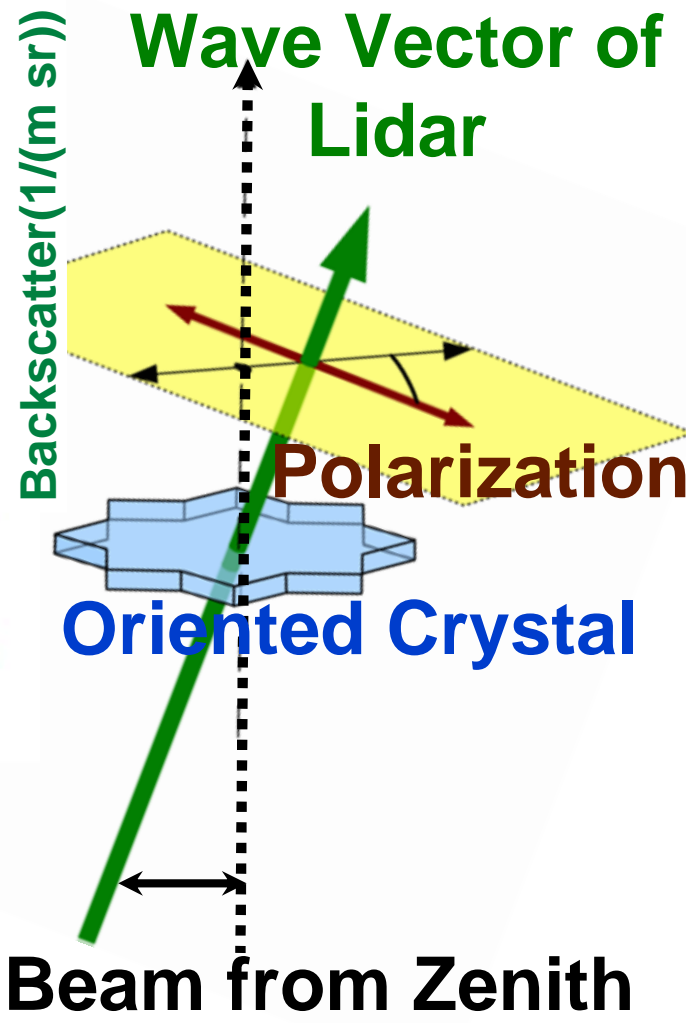
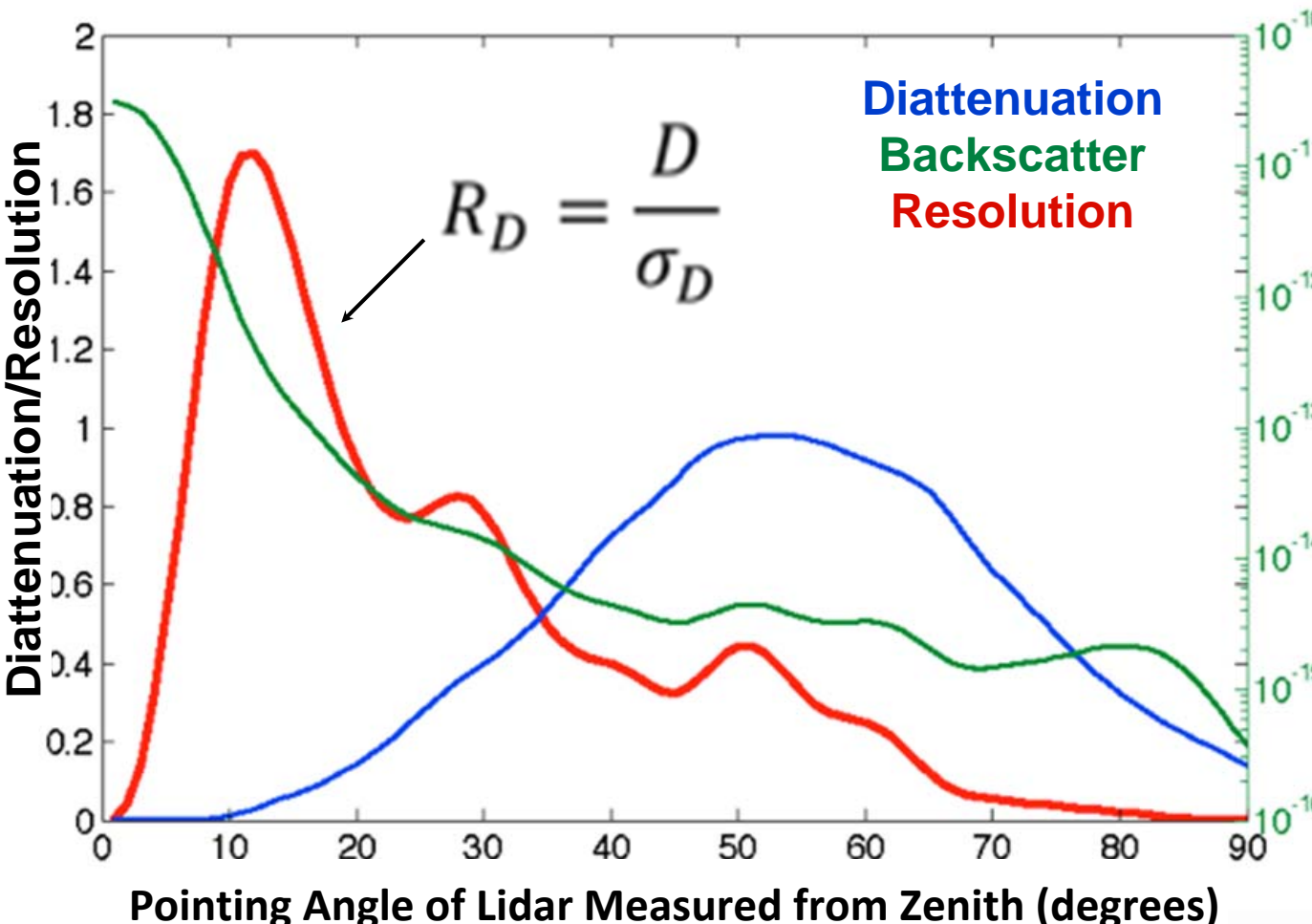
- Summit Station
 - Peak of the Greenland Ice Cap (3.2km a.s.l)
 - 400km from coast
 - $72^{\circ}34'44.10''\text{N}$ $38^{\circ}27'34.56''\text{W}$



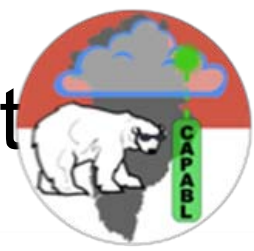
NSF's Mobile Science Facility



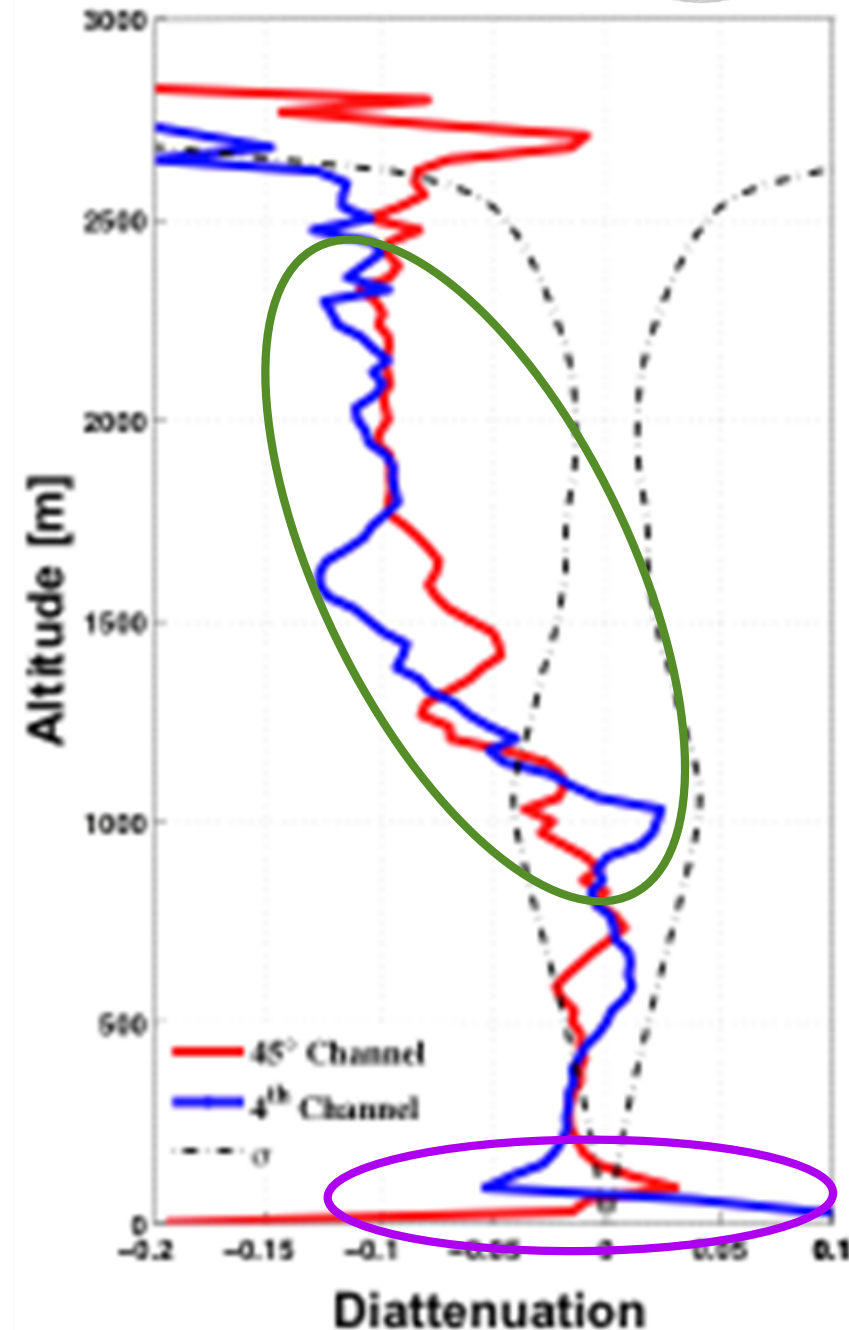
Ability to measure oriented ice crystals is dependent on pointing angle of lidar.



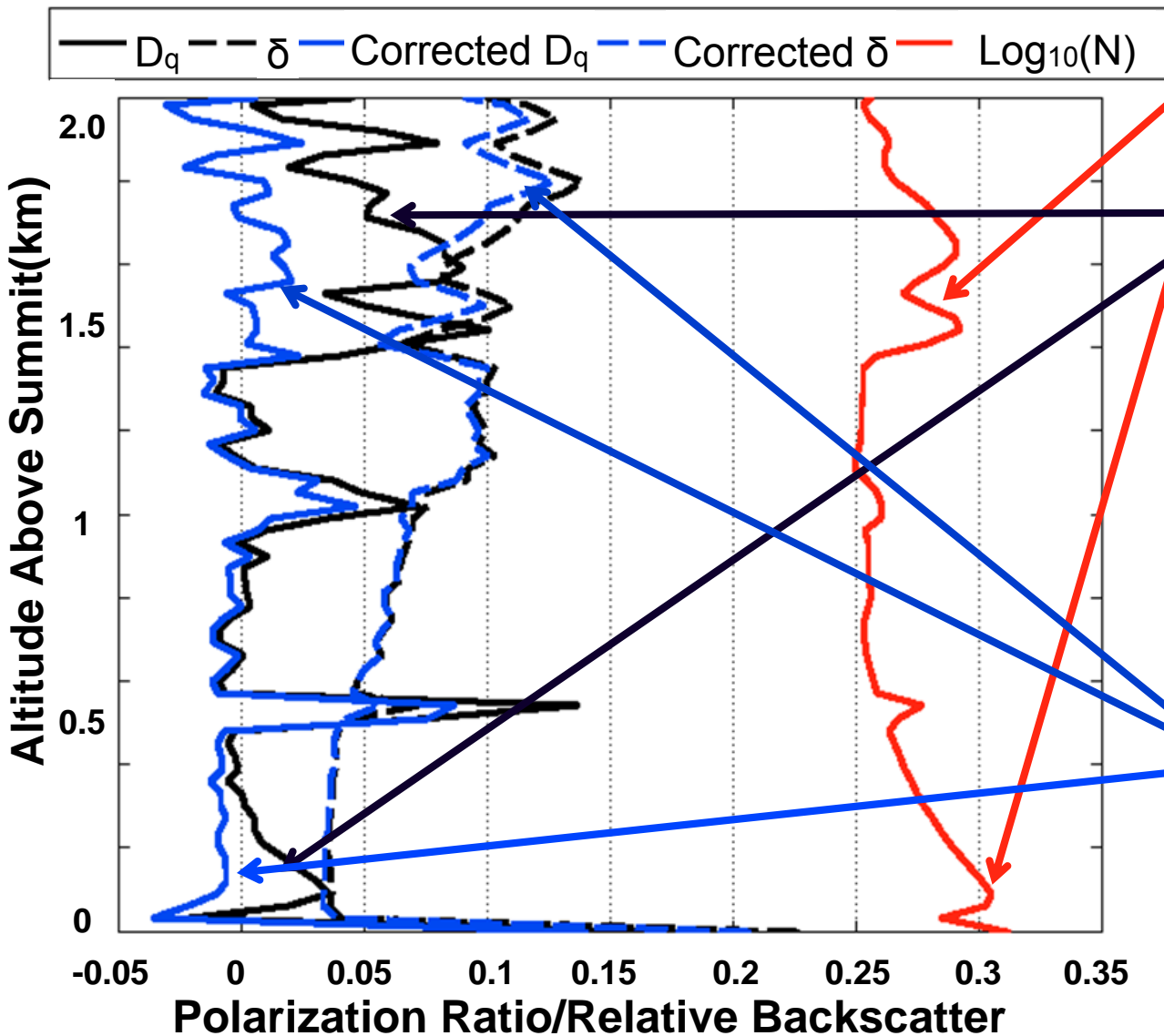
Self Validation of Diattenuation Measurement Against Instrumental Effects



- **Integrated profile** from 5:30 to 6:00 UTC on February 18, 2012 (a section from the whole day shown in **pervious slide**).
- Using the liquid crystal rotator we can make a **second** measure of diattenuation using another set of off diagonal elements form the scattering matrix.
- This allows for the **two measures of diattenuation** to be **influenced differently by detector saturation**.
- Regions where **both diattenuation profiles track together**, above the error limits, contain **positive detection of diattenuating scatterers**.
- Regions where the two diattenuation profiles **behave oppositely**, as is seen in the bottom of the profile, is due to **detector saturation**.



Diattenuation help lidar observations to be more accurate in other ways.



Strong Backscatter introduces **error** to data products due to nonlinear detector gain (pulse pile up).

Nonlinearity may be solved for because diattenuation detected in zenith direction is defined as zero.

Corrected backscatter counts produce **more accurate** data products.

Dynamic range of backscatter detection is increased by an order of magnitude.